

## EAST Search History

## EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	0	(transmitter and receiver) same (computer or CPU or controller or (micro processor) or processor) same (independent) same (proximity or close or distance or seperation) same (effector or grip or hand or arm) same (robot) same (orientation)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2010/06/22 19:22
L2	0	(transmitter and receiver) same (computer or CPU or controller or (micro processor) or processor) same (independent) same (proximity or close or distance or seperation) same (effector or grip or hand or arm) same (robot) same (orientation).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2010/06/22 19:22
L4	3	"6330503".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2010/06/22 19:34
L5	2	"US 20060155459"	US-PGPUB; USPAT; USOCR; DERWENT	ADJ	ON	2010/06/22 19:44
S1	2	"US 20060155459"	US-PGPUB; USPAT; USOCR; DERWENT	ADJ	ON	2009/10/05 14:51

S2	9831	"901"/\$.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 15:28
S3	4002	700/245-264.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 15:30
S4	9536	342/104-158.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 15:31
S5	25184	342/350-458.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 15:33
S6	2489	(S2 or S3 or S4 or S5) and ((move or movement or adjust or change) same (position or location or place or area or point) same (reference or grid or standard) same (arm or effector or robot))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 15:41
S7	13	(S2 or S3 or S4 or S5) and ((move or movement or adjust or change) same (position or location or place or area or point) same (reference or grid or standard) same (arm or effector or robot)) same (GPS)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 15:42

S8	23	("4477754"   "4611292"   "5049796"   "5305427"   "5404661"   "5438771"   "5692412"   "5694813"   "5811951"   "5831408"   "5845540"   "5871248"   "5893296"   "5946449"   "6032084"   "6035254"   "6074164"   "6105455").PN. OR ("6898484").URPN.	US-PGPUB; USPAT; USOCR	ADJ	ON	2009/10/05 16:16
S9	16	("20040260422"   "3241687"   "4505166"   "5129044"   "5429015"   "5553509"   "5784282"   "5845540"   "5893296"   "6105455"   "6347259"   "6424077"   "6681145"   "6701196"   "6898484").PN. OR ("7259535").URPN.	US-PGPUB; USPAT; USOCR	ADJ	ON	2009/10/05 16:21
S10	53	(robot same arm same (calibration with (automatic or auto or self)))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 16:40
S11	0	(robot same arm same (calibration with (automatic or auto or self))) same (GPS)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 16:41
S12	0	(robot same arm same (calibration with (automatic or auto or self))) and (GPS)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/10/05 16:41
S13	2	"US 20060155459"	US-PGPUB; USPAT; USOCR; DERWENT	ADJ	ON	2009/10/08 19:59

**EAST Search History (I nterference)**

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L3	0	(transmitter and receiver) same (computer or CPU or controller or (micro processor) or processor) same (independent) same (proximity or close or distance or seperation) same (effector or grip or hand or arm) same (robot) same (orientation).clm.	US-PGPUB; USPAT; UPAD	ADJ	ON	2010/06/22 19:22

**6/ 22/ 2010 8:24:32 PM**

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& device for handling an object with the aid of a location system\_Amended.wsp**